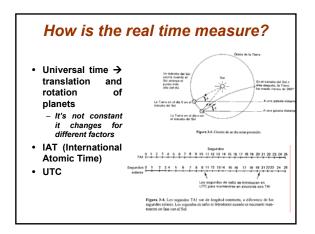
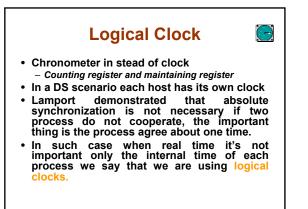


## **General concepts**

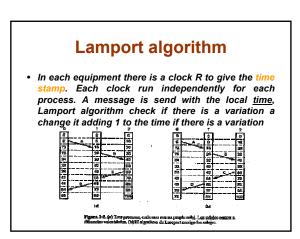
- The distributed algorithms have the some properties that makes coordination a key for process communication:
  - Information is distributed around host
  - Process takes decisions based in local information
  - One point of failure must be avoided (single host)
     There is not global clock
- The last point is we are going to talking about
  - It's possible to synchronize clocking in a DS?

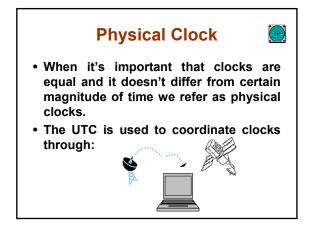


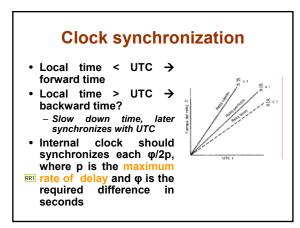


# Synchronization in logical clocks

- Lamport defined the relation "it happens before" a →b, where a happens before b. For this purpose the process need to agree what event happen before.
- In the case of distributed process it happen the same with message that arrive



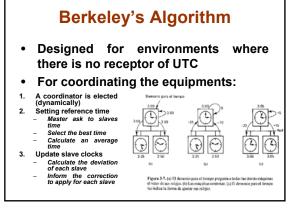




## **Cristian's Algorithm**

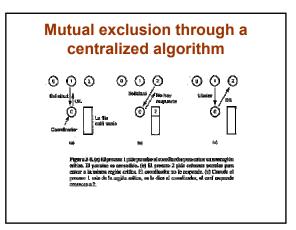
- Designed for equipment where a sever is sync through UTC
- Each φ/2p seconds equipments send to server request of time
- This algorithm should consider the time of propagation through the network:

- Sync time =  $T_{utc} + ((T_r - T_e - I) / 2)$ 

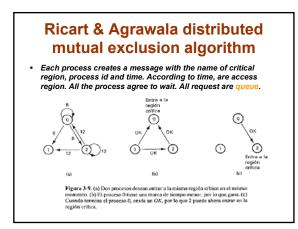


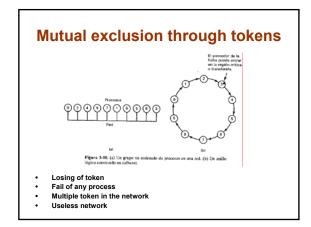


- neck, etc
  Another view consider that equipments
  - resync periodically
  - For each I<sub>t</sub> interval each node send time
  - Wait for time arriving or reach maximum delay
    - Discard extreme valuesCalculate an average time
  - Update local time with the computed value
  - All local clock get updated



#### RR1 Especificado por el fabricante Rafael Rojano, 02/04/2008





Algoritgm	Message send	Message delay	problems
Centralized	3	2	Coordinator fail
Distributed	2(n-1)	2(n-1)	Fail of any process
Token ring	1 a ∞	0 a n-1	Token lost, process fai

## **Election**

- Many of the seen algorithm require election for a coordinator
- This algorithms are:
  - Bully algorithm
  - Ring algorithm

