

# SOME FRACTIONAL DIFFERENTIAL EQUATIONS ON MATHEMATICAL BIOLOGY

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**4th Mexican Workshop in Fractional Calculus**

1 FIREFLIES

2 CIRCADIAN RHYTHM

3 DYNAMICS POPULATIONS

# BIOLOGICAL ASSUMPTIONS AND CONSIDERATIONS OF THE MATHEMATICAL MODEL

- Natural rhythm on-off, Van der Pol oscillator

# BIOLOGICAL ASSUMPTIONS AND CONSIDERATIONS OF THE MATHEMATICAL MODEL

- Number of competitors and distance to them

# BIOLOGICAL ASSUMPTIONS AND CONSIDERATIONS OF THE MATHEMATICAL MODEL

- Memory system: Fractional Differential Equations

$$\begin{aligned}\ddot{x}_i &= f_i(x_i, \dot{x}_i) + \sum_{j \neq i} a_{ij} x_j, \quad (1 \leq i, j \leq 4), \\ f_i(x_i, \dot{x}_i) &= \mu(1 - x_i^2) \dot{x}_i - a_{ii} x_i.\end{aligned}\tag{1}$$

The parameter  $a_{ij}$ , is the influence firefly  $i$  experiencing due to the brightness of the firefly  $j$ . Let be  $a_{ii} = k$ .

$$\ddot{x}_i = f_i(x_i, \dot{x}_i) + \sum_{j \neq i} a_{ij} x_j, \quad (1 \leq i, j \leq 4), \quad (1)$$

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The system (1) is expressed in a canonical form using the change of variables as follow:  $z_1 = x_1$ ,  $z_2 = \dot{x}_1$ ,  $z_3 = x_2$ ,  $z_4 = \dot{x}_2$ ,  $z_5 = x_3$ ,  $z_6 = \dot{x}_3$ ,  $z_7 = x_4$  and  $z_8 = \dot{x}_4$ , now the system is given by:

$$\dot{z}_{2i-1} = z_{2i}, \quad \dot{z}_{2i} = f_{2i-1}(z_{2i-1}, z_{2i}) + \sum_{\substack{s \neq i \\ 2j-1 \neq 2i-1}} a_{is} z_{2j-1}, \quad (2)$$

$$1 \leq s, i, j \leq 4.$$

# SYSTEM OF FRACTIONAL DIFFERENTIAL EQUATIONS

$${}_0^C D_t^\gamma z_{2i-1} = z_{2i}, \quad {}_0^C D_t^\gamma z_{2i} = f_{2i-1}(z_{2i-1}, z_{2i}) + \sum_{\substack{s \neq i \\ 2j-1 \neq 2i-1}} a_{is} z_{2j-1}, \quad (3)$$

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The Liouville-Caputo operator defining the fractional derivative for ( $\gamma > 0$ ) as

$${}_0^C \mathcal{D}_t^\gamma f(t) = \frac{1}{\Gamma(n - \gamma)} \int_0^t \frac{f^{(n)}(\eta)}{(t - \eta)^{\gamma - n + 1}} d\eta, \quad (4)$$

where  ${}_0^C \mathcal{D}_t^\gamma$  is a Liouville-Caputo fractional derivative with respect to  $t$ .



# SYSTEM OF FRACTIONAL DIFFERENTIAL EQUATIONS

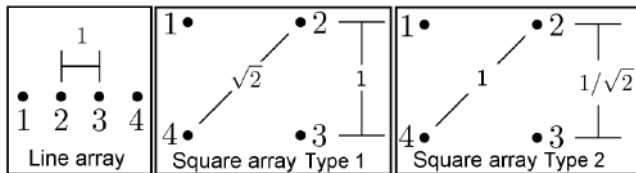
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# LINEAR ARRAY. ONE OR TWO COMPETITORS

System linearization (3) around of the equilibrium point  $0 \in \mathbb{R}^8$  in terms of the parameters  $k, \mu$  is defined by  $M_1$

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ -k & \mu & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & -k & \mu & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & -k & \mu & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 & -k & \mu \end{bmatrix}$$

The eigenvalues of  $M_1$  are  $1/2(\mu \pm \sqrt{\pm 2 \pm \sqrt{5} - 4k + \mu^2})$ . Since a periodic phenomenon modeled complex eigenvalues are needed and therefore

$$\begin{aligned} k &> \max \left\{ \frac{1}{4}(\mu^2 \pm 2 \pm 2\sqrt{5}) \right\} \\ &= \frac{1}{4}(\mu^2 + 2 + 2\sqrt{5}) \\ &\approx 1.868033989. \end{aligned}$$

## SQUARE ARRAY. TYPE 1

System linearization (3) around of the equilibrium point  $0 \in \mathbb{R}^8$  in terms of the parameters  $k, \mu$  is defined by  $M_2$

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ -k & \mu & 1 & 0 & 1/2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & -k & \mu & 1 & 0 & 1/2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1/2 & 0 & 1 & 0 & -k & \mu & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 1 & 0 & 1/2 & 0 & 1 & 0 & -k & \mu \end{bmatrix}$$

The eigenvalues of  $M_2$  are  $1/2(\mu \pm \sqrt{-6 - 4k + \mu^2})$ ,  $1/2(\mu \pm \sqrt{10 - 4k + \mu^2})$  and  $1/2(\mu \pm \sqrt{-2 - 4k + \mu^2})$  of algebraic multiplicity 2. Thus

$$\begin{aligned} k &> \max \left\{ \frac{1}{4}(\mu^2 - 6), \right. \\ &\quad \left. \frac{1}{4}(\mu^2 + 10), \frac{1}{4}(\mu^2 - 2) \right\} \\ &= \frac{1}{4}(\mu^2 + 10) = 2.75 \end{aligned}$$

## SQUARE ARRAY. TYPE 2

System linearization (3) around of the equilibrium point  $0 \in \mathbb{R}^8$  in terms of the parameters  $k, \mu$  is defined by  $M_3$

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ -k & \mu & 1/2 & 0 & 1 & 0 & 1/2 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 1/2 & 0 & -k & \mu & 1/2 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 1/2 & 0 & -k & \mu & 1/2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 1/2 & 0 & 1 & 0 & 1/2 & 0 & -k & \mu \end{bmatrix}$$

The eigenvalues of  $M_3$  are  $1/2(\mu \pm \sqrt{-4 - 4k + \mu^2})$  of multiplicity 2,  $1/2(\mu \pm \sqrt{-4k + \mu^2})$  and  $1/2(\mu \pm \sqrt{8 - 4k + \mu^2})$ . Thus

$$\begin{aligned} k &> \max \left\{ \frac{1}{4}(\mu^2 - 4), \right. \\ &\quad \left. \frac{1}{4}(\mu^2), \frac{1}{4}(\mu^2 + 8) \right\} \\ &= \frac{1}{4}(\mu^2 + 8) = 2.25 \end{aligned}$$

# RESULTS AND CONCLUSIONS

## RESULTS

- For the linear arrangement, where the fireflies only see one or two fireflies, the value of  $k = 1.868033989$ .
- For the square array type 1,  $k = 2.75$ .
- For the square array type 2,  $k = 2.25$ .
- For the linear array, where each receives three,  $k = 2.1322$ .

## CONCLUSIONS

The value of  $k$  means the effort that each firefly makes to shine, this value increases when the number of competitors increases (fixed distance). In addition, it decreases when the distance between them is smaller (number of fixed competitors)

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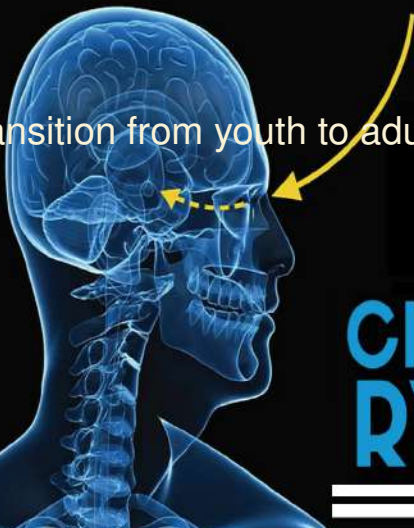
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- Oscillator communication



# CIRCADIAN RYTHM

- Transition from youth to adult



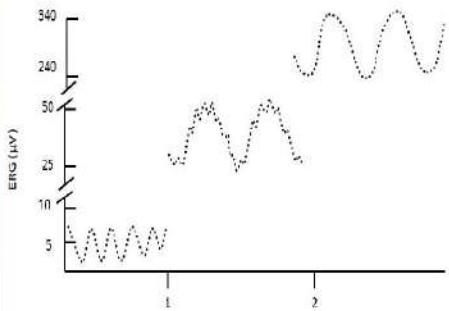
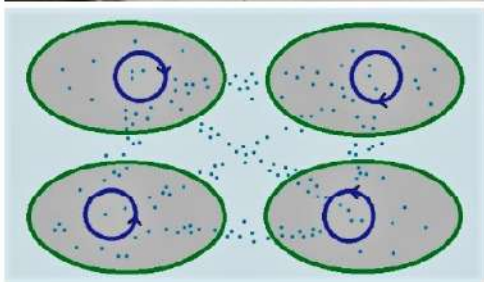
# CIRCADIAN RYTHM



- Synchronization of ultradian rhythms in a circadian rhythm



# CIRCADIAN RYTHM



## $\mu$ , IT IS A PARAMETER OF COMMUNICATION EFFICIENCY BETWEEN RHYTHMS

$$\begin{aligned}
 \ddot{x}_1 &= \nu(1 - x_1^2)\dot{x}_1 - kx_1 + \mu(a_{12}x_2 + a_{13}x_3 + a_{14}x_4), \\
 \ddot{x}_2 &= \nu(1 - x_2^2)\dot{x}_2 - kx_2 + \mu(a_{21}x_1 + a_{23}x_3 + a_{24}x_4), \\
 \ddot{x}_3 &= \nu(1 - x_3^2)\dot{x}_3 - kx_3 + \mu(a_{31}x_1 + a_{32}x_2 + a_{34}x_4), \\
 \ddot{x}_4 &= \nu(1 - x_4^2)\dot{x}_4 - kx_4 + \mu(a_{41}x_1 + a_{42}x_2 + a_{43}x_3).
 \end{aligned} \tag{5}$$

The coefficients  $a_{ij}$  in (5) they are given by the following matrix

$$\begin{bmatrix} -k & 1 & 1/\sqrt[4]{2} & 1 \\ 1 & -k & 1 & 1/\sqrt[4]{2} \\ 1/\sqrt[4]{2} & 1 & -k & 1 \\ 1 & 1/\sqrt[4]{2} & 1 & -k \end{bmatrix}. \tag{6}$$

The **Liouville-Caputo** fractional derivative of order  $\gamma$  is defined by

$${}^aLC\mathcal{D}_t^\gamma\{f(t)\} = \frac{1}{\Gamma(n-\gamma)} \int_a^t f^{(n)}(\theta)(t-\theta)^{n-\gamma-1}d\theta, \quad n-1 < \gamma \leq n. \quad (7)$$

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By changing the kernel  $(t-\theta)^{-\gamma}$  in (7) with the function  $\exp(-\frac{\gamma}{n-\gamma}t)$  and  $\frac{1}{\Gamma(n-\gamma)}$  with  $\frac{M(\gamma)}{n-\gamma}$ , it is obtained the **Caputo-Fabrizio** fractional derivative:

$${}^{CF} \mathcal{D}_t^\gamma \{f(t)\} = \frac{M(\gamma)}{n-\gamma} \int_a^t f^{(n)}(\theta) \exp\left[-\frac{\gamma}{n-\gamma}(t-\theta)\right] d\theta, \quad n-1 < \gamma \leq n. \quad (8)$$

Where  $M(\gamma)$  is a normalization function such that  $M(0) = M(1) = 1$ .

# RHYTHMS: ELECTRORETINOGRAPHY (ERG) VS STAGES OF CRAYFISH

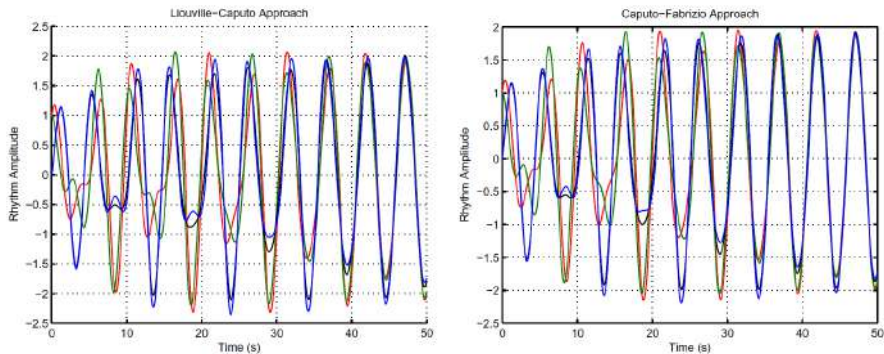


FIGURE:  $\mu = 0.5$ ,  $\gamma = 0.9, 0.85, 0.8, 0.75$ .

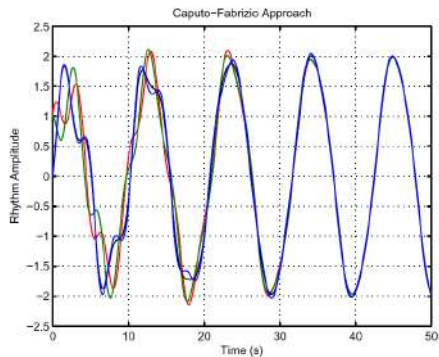
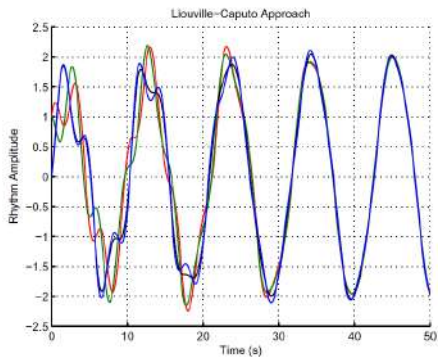


FIGURE:  $\mu = 0.8, \gamma = 0.9, 0.85, 0.8, 0.75$ .

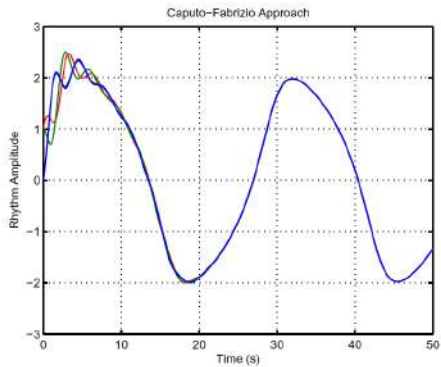
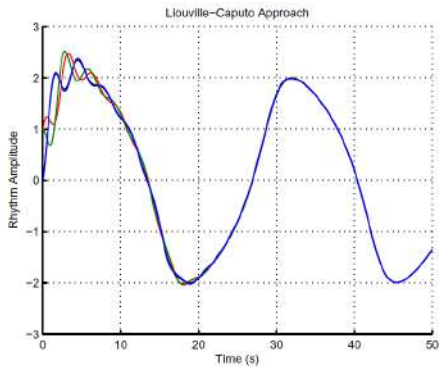


FIGURE:  $\mu = 1$ ,  $\gamma = 0.9, 0.85, 0.8, 0.75$ .



# CONCLUSIONS

- $0 < \mu < 0.7$ . Ultradian rhythms shown at this stage are clearly out of synchrony.
- $0.7 < \mu < 1$ . A low frequency rhythm appears on which ultradian rhythms can be observed that correspond to stage 1-2.
- $\mu = 1$ . The crayfish is mature, the circadian rhythm is more apparent. In fact, ultradian rhythms are synchronized in a single circadian rhythm responsible for governing the metabolism of the adult crayfish.

# DYNAMICS IN NATURAL TIME

- Interaction of three species: Pollinators, plants, herbivores

# DYNAMICS IN NATURAL TIME



- Persistence of a Hopf bifurcation

# DYNAMICS IN NATURAL TIME

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- The mathematical model it is by Fractional derivatives to include ecological hypotheses

## DEFINITION

Caputo fractional derivative with order  $\alpha$  for a function  $f \in \mathcal{AC}^m[0, T]$ ,  $T > 0$  with absolutely continuous derivative up to order  $m - 1$  and with absolutely continuous  $m$ -derivative is defined as

$${}^C D_{t_0}^\alpha f(t) = \frac{1}{\Gamma(m - \alpha)} \int_{t_0}^t (t - \tau)^{m-\alpha-1} f^{(m)}(\tau) d\tau. \quad (9)$$

where  $0 \leq m - 1 < \alpha \leq m$ ,  $m \in \mathbb{Z}^+$ , and  $t = t_0$  is the initial time and  $\Gamma(\cdot)$  is the Gamma function.  $f^{(m)}$  is the derivative of  $f$  of order  $m$ .

To keep the dimensionality of the system of fractional differential equations, we introduce a parameter  $\nu$ , named “natural time”, in the following way. **The specific value that the natural time takes depends on each investigation, this should be a unit defined by the own biological rhythms of the studied system.**

$$\begin{aligned} \frac{df}{dt} &\simeq \frac{1}{\nu^{1-\alpha}} \frac{d^\alpha f}{dt^\alpha}, \\ &= \frac{1}{\nu^{1-\alpha}} {}^C D_{t_0}^\alpha f(t), \end{aligned} \quad m-1 < \alpha \leq m, \quad m \in \mathbb{Z}^+. \quad (10)$$

# SYSTEM OF FRACTIONAL DIFFERENTIAL EQUATIONS

The system is derived on some plausible and widely supported ecological hypothesis. Respectively:  $x$ -pollinator,  $y$ -plants and  $z$ -herbivores.

$$\begin{aligned}
 \frac{1}{\nu^{1-\alpha}} \frac{d^\alpha x}{dt^\alpha} &= bx(k-x) + \frac{g(z)k_2\sigma\mu^2xy}{1+\phi\sigma\mu^2y}, \\
 \frac{1}{\nu^{1-\alpha}} \frac{d^\alpha y}{dt^\alpha} &= \frac{g(z)k_1\sigma\mu xy}{1+\phi\sigma\mu^2y} - \gamma y - \frac{m_1yz}{\frac{y^2}{c} + y + a}, \\
 \frac{1}{\nu^{1-\alpha}} \frac{d^\alpha z}{dt^\alpha} &= \frac{m_2yz}{\frac{y^2}{c} + y + a} - \delta z.
 \end{aligned} \tag{11}$$

where  $x(0) \geq 0, y(0) \geq 0, z(0) \geq 0$ , and  $g(z)$  measures the reduction rate of pollinator visits, which depends on the herbivore population density

## STABILITY ANALYSIS

$$M(x, yz) =$$

$$\begin{bmatrix} b(k - 2x) + \mu k_2 y h_2(y) & \mu k_2 x h_3(y) & 0 \\ k_1 y h_2(y) & k_1 x h_3(y) + m_1 y(2y + c)h_6(y) - m_1 z h_5(y) - \gamma & -m_1 y h_5(y) \\ 0 & m_2 z h_5(y) - m_2 y z(2y + c)h_6(y) & -m_2 y h_5(y) - \delta \end{bmatrix}$$

$$\text{with } h_1(y) = y\sigma\phi\mu^2 + 1, h_2(y) = \frac{g(z)\sigma\mu}{h_1(y)}, h_3(y) = \frac{h_2(y)}{h_1(y)},$$

$$h_4(y) = y^2 + cy + ac, h_5(y) = \frac{c}{h_4(y)}, h_6(y) = \frac{h_5(y)}{h_4(y)}.$$



TABLE: Equilibrium points of the system (11)

| $x$    | $y$     | $z$       | Plausible |
|--------|---------|-----------|-----------|
| 0.6666 | -2.0    | 0         | ×         |
| 0      | 22.4888 | -187.4066 | ×         |
| 0      | 0.1778  | -1.4822   | ×         |
| 0.9664 | -0.1141 | 0         | ×         |
| 2.9183 | 0.1778  | 1.0702    | ✓         |
| 0      | 0       | 0         | ×         |
| 5.4238 | 22.4888 | -169.7203 | ×         |
| 0      | -0.5    | 0         | ×         |
| 2      | 0       | 0         | ×         |
| 0      | -2.0    | 0         | ×         |
| 4.5353 | 1.3141  | 0         | ×         |

$$N(p) = \begin{bmatrix} -3.7695 & 14.3579 & 0 \\ 0.3388 & -1.0776 & -0.3874 \\ 0 & 2.9263 & -0.0002 \end{bmatrix} \quad (12)$$

$$\lambda_1 = -4.9544$$

$$\lambda_2 = 0.0536 + 0.9271 i \quad (13)$$

$$\lambda_2 = 0.0536 - 0.9271 i$$

When  $\alpha \in (0, 0.9625]$ ,  $p$  is a spiral stable. For  $\alpha \in (0.9625, 1]$  system has a limit cycle.

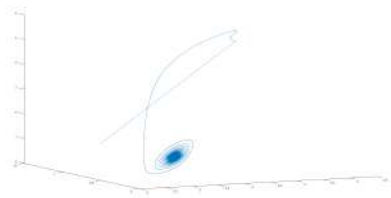


FIGURE: Spiral

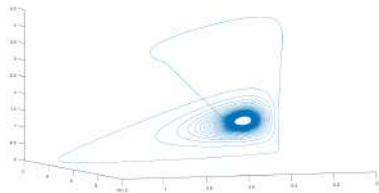


FIGURE: Limit Cycle

# CONCLUSIONS

- Stability in both cases is plausible from the ecological perspective.
- Varying the order of derivation causes a Hopf fork to appear.
- The derivation orders can be different between equations in the numerical method used.

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*Thank you  
very much  
for your attention*